

# Conformal Maps

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Complex Variables

## Definition

A (*parametric*) curve in  $\mathbb{C}$  is a continuous function  $\gamma : (0, 1) \rightarrow \mathbb{C}$ . If  $x(t) = \operatorname{Re} \gamma(t)$  and  $y(t) = \operatorname{Im} \gamma(t)$ , we say  $\gamma$  is a  $C^k$  curve provided  $x(t), y(t) \in C^k((0, 1))$ .

## Remarks.

- 1 One frequently identifies  $\gamma$  with its image  $C = \gamma((0, 1))$ . Strictly speaking, however, the former is a *description* of the latter.
- 2 Because all open intervals in  $\mathbb{R}$  are diffeomorphic,  $(0, 1)$  can be replaced by any other open interval.

# Examples

- 1  $\gamma(t) = t + i(mt + b)$ ,  $t \in \mathbb{R}$ , is a smooth parametrization of the line  $y = mx + b$ .
- 2  $\gamma(t) = te^{i\theta_0}$ ,  $t \in (0, \infty)$ , is a smooth parametrization of the ray  $\arg z = \theta_0$ .
- 3  $\gamma(t) = e^{it}$ ,  $t \in \mathbb{R}$ , is a smooth parametrization of the unit circle.
- 4  $\gamma(t) = t^2 + it$ ,  $t \in \mathbb{R}$ , parametrizes the rightward opening parabola  $x = y^2$ .

# Tangent Vectors

## Definition

If  $\gamma(t) = x(t) + iy(t)$  is a  $C^1$  curve, its *derivative* is

$$\gamma'(t) = x'(t) + iy'(t),$$

which is the familiar *tangent vector* in  $\mathbb{R}^2$ .

Notice that

$$\begin{aligned}\gamma'(t) &= \left( \lim_{h \rightarrow 0} \frac{x(t+h) - x(t)}{h} \right) + i \left( \lim_{h \rightarrow 0} \frac{y(t+h) - y(t)}{h} \right) \\ &= \lim_{h \rightarrow 0} \frac{x(t+h) + iy(t+h) - x(t) - iy(t)}{h} \\ &= \lim_{h \rightarrow 0} \frac{\gamma(t+h) - \gamma(t)}{h}.\end{aligned}$$

# Compositions

Let  $\Omega \subset \mathbb{C}$  be a domain and let  $f : \Omega \rightarrow \mathbb{C}$  be analytic.

If  $\gamma$  is a curve in  $\Omega$ , then its image under  $f$ , namely  $\Gamma = f \circ \gamma$ , is also a curve.

If  $\gamma$  is  $C^1$ , then for any  $t$ :

$$\begin{aligned}\Gamma'(t) &= \lim_{h \rightarrow 0} \frac{\Gamma(t+h) - \Gamma(t)}{h} \\ &= \lim_{h \rightarrow 0} \frac{f(\gamma(t+h)) - f(\gamma(t))}{h} \\ &= \lim_{h \rightarrow 0} \frac{f(\gamma(t+h)) - f(\gamma(t))}{\gamma(t+h) - \gamma(t)} \cdot \frac{\gamma(t+h) - \gamma(t)}{h} \\ &= f'(\gamma(t))\gamma'(t),\end{aligned}$$

so that  $\Gamma$  is also  $C^1$  with derivative given by the chain rule.

# Summary

## Theorem 1 (Chain Rule for Curves)

*Suppose  $f$  is analytic at  $z_0$  and  $\gamma$  is any curve through  $z_0$ . Then the tangent vector to the image curve  $\Gamma = f \circ \gamma$  at  $f(z_0)$  is  $f'(z_0)$  (complex) multiplied by the tangent vector to  $\gamma$  at  $z_0$ .*

Geometrically speaking, this is saying that locally  $f$  dilates and rotates tangent vectors, by  $|f'|$  and  $\arg f'$  (resp.).

This provides a geometric interpretation of  $f'(z_0)$ .

This can also be seen in the Jacobian. If  $f'(z_0) = u_x + iv_x = re^{i\theta}$ :

$$J_f(z_0) = \begin{pmatrix} u_x & -v_x \\ v_x & v_y \end{pmatrix} = \underbrace{\begin{pmatrix} r & 0 \\ 0 & r \end{pmatrix}}_{\text{scalar}} \underbrace{\begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}}_{\text{rotation}}.$$

# Angles

Now suppose curves  $\gamma_1$  and  $\gamma_2$  in  $\Omega$  intersect at  $z_0 = \gamma_1(t_1) = \gamma_2(t_2)$ .

The angle  $\varphi$  between  $\gamma_1$  and  $\gamma_2$  at  $z_0$  is defined to be the angle between the tangent vectors  $\gamma_1'(t_1)$  and  $\gamma_2'(t_2)$ , or

$$\varphi = \arg(\gamma_2'(t_2)) - \arg(\gamma_1'(t_1)) = \arg(\gamma_2'(t_2)/\gamma_1'(t_1)).$$

Notice that  $\varphi$  is not symmetric in  $\gamma_1$  and  $\gamma_2$ . So our angles come with an *orientation*: counterclockwise from  $\gamma_1$  to  $\gamma_2$ .

Let  $f$  be analytic at  $z_0$ . Let  $\Gamma_j = f \circ \gamma_j$  be the image of  $\gamma_j$  under  $f$  ( $j = 1, 2$ ). These intersect at  $w_0 = f(z_0) = \Gamma_1(t_1) = \Gamma_2(t_2)$ .

The tangent vectors at  $w_0$  are  $\Gamma'(t_j) = f'(z_0)\gamma'_j(t_j)$ , by the chain rule.

If  $f'(z_0) \neq 0$ , the angle between the image curves  $\Gamma_1$  and  $\Gamma_2$  is

$$\begin{aligned}\varphi' &= \arg (\Gamma'_2(t_2)/\Gamma'_1(t_1)) \\ &= \arg \left( \frac{f'(z_0)\gamma'_2(t_2)}{f'(z_0)\gamma'_1(t_1)} \right) \\ &= \arg (\gamma'_2(t_2)/\gamma'_1(t_1)) \\ &= \varphi.\end{aligned}$$

Thus,  $f$  preserves the angles between tangent vectors at each point! (In both magnitude *and* orientation).



# Conformality

## Definition

Let  $\Omega \subset \mathbb{R}^2$  be a domain. A map  $\Omega \rightarrow \mathbb{R}^2$  is called *conformal* if it preserves angles (in magnitude and orientation) at every point in  $\Omega$ .

We have now seen:

## Theorem 2

*An analytic function  $f(z)$  is conformal everywhere that  $f'(z) \neq 0$ .*

As an easy non-example we have:

## Example 1

The function  $f(z) = \bar{z}$  is *not* conformal.

This is simply because reflections *reverse* the orientations of angles.

# Examples

Example 2

$z^2$  and  $\sqrt{z}$

Example 3

$e^z$  and  $\log z$

Example 4

$\sin z$

Example 5

$1/z$

(See Maple)