EXPLICIT INVERSION FORMULAS FOR TOEPLITZ BAND MATRICES*

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Abstract. Explicit formulas are given for the elements of T_n^{-1} and the solution of $T_nX = Y$, where T_n is an $(n+1) \times (n+1)$ Toeplitz band matrix with bandwidth $k \le n$. The formulas involve $k \times k$ determinants whose entries are powers of the zeros of a certain kth degree polynomial P(z) which is independent of n, or simple related functions of these zeros if any are repeated. It is shown that T_n is invertible if and only if a certain $k \times k$ determinant involving these zeros is nonvanishing.

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1. Introduction. We consider Toeplitz band matrices, i.e., matrices of the form

$$T_n = (\phi_{r-s})_{r,s=0}^n$$

where there are nonnegative integers p and q such that

(1)
$$\phi_{\nu} = 0 \quad \text{if } \nu > p \text{ or } \nu < -q.$$

We use the notation of [13] and [15]. Notice that T_n is of order n+1, with rows and columns numbered from 0 to n. We write

$$T_n^{-1} = B_n = (b_{rsn})_{r,s=0}^n$$

It is assumed throughout that

(2)
$$\phi_p \phi_{-q} \neq 0 \quad \text{and} \quad p + q = k \le n.$$

Our main results are explicit formulas for the elements of T_n^{-1} and for the solution of the system

$$(3) T_n X = Y,$$

in terms of the zeros of the polynomial

(4)
$$P(z) = \sum_{\mu = -q}^{p} \phi_{\mu} z^{\mu + q}.$$

These formulas involve determinants of order k, the bandwidth of T_n .

Many authors (e.g., [1], [3], [6], [7], [9], [10], [12], [15]) have given formulas and algorithms for inverting Toeplitz band matrices. Efficient methods have also been developed for solving (3) (e.g., [2], [4], [11], [14]). Since a survey of results along these lines is given in the introduction to the recent paper [9], there is no need to review earlier work here. We believe that the results presented here are new, and more general and explicit than others heretofore published. We treat the general Toeplitz band matrix, without assuming that T_n is symmetric or hermitian. Our formulas are explicit (i.e., not recursive with respect to n), and we do not have to assume that any matrix other than T_n is nonsingular; however, we do give a method for computing T_n^{-1} efficiently in the case where T_{n-1} is also nonsingular.

The idea motivating our approach is that if n is large compared to k, then T_n is "nearly triangular" in an obvious visual sense, which need not be defined precisely.

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Therefore, it is not surprising that the elements of T_n^{-1} are closely related to those of $(T_n^L)^{-1}$, where T_n^L is the lower triangular Toeplitz matrix

$$T_n^L = (\phi_{r-s-q})_{r,s=0}^n$$

The inverse of this matrix is the lower triangular Toeplitz matrix

(5)
$$(T_n^L)^{-1} = (\alpha_{r-s})_{r,s=0}^n \qquad (\alpha_{\nu} = 0 \text{ if } \nu < 0),$$

with elements independent of n, defined by

(6)
$$(P(z))^{-1} = \sum_{\nu=0}^{\infty} \alpha_{\nu} z^{\nu}.$$

It is easy to find an explicit formula for α_{ν} in terms of the zeros of P(z). Moreover, we will show that the differences

$$b_{rsn} - \alpha_{r-s-q}, \quad 0 \leq r, s \leq n$$

can be found easily and explicitly in terms of the zeros of P(z). This leads to explicit formulas for T_n^{-1} and the solution of (3).

We also give analogous formulas based on the inverse of the upper triangular Toeplitz matrix

$$T_n^U = (\phi_{r-s+p})_{r,s=0}^n$$

The inverse of this matrix is

(7)
$$(T_n^U)^{-1} = (\beta_{s-r})_{r,s=0}^n \qquad (\beta_{\nu} = 0 \text{ if } \nu < 0),$$

with elements independent of n, defined by

(8)
$$\left(z^k P\left(\frac{1}{z}\right)\right)^{-1} = \sum_{\nu=0}^{\infty} \beta_{\nu} z^{\nu}.$$

2. Preliminary results. The following assumption applies throughout. (Recall (2) here.)

Assumption A. The distinct zeros of (4) are z_1, \dots, z_m , with multiplicities μ_1, \dots, μ_m ; thus, $m \le k$, $\mu_i \ge 1$, and

$$\mu_1+\cdots+\mu_m=k.$$

DEFINITION 1. If j_1, \dots, j_k are integers, let

$$C(z; j_1, \cdots, j_k) = \operatorname{col}[z^{j_1}, \cdots, z^{j_k}],$$

and let $C^{(l)}(z;j_1,\cdots,j_k)$ denote the lth derivative of this column vector. Now define the $k\times k$ determinant $D(j_1,\cdots,j_k)$ as follows: Its first μ_1 columns are $C^{(l)}(z_1;j_1,\cdots,j_k)(0\leq l\leq \mu_1-1)$; it next μ_2 columns are $C^{(l)}(z_2;j_1,\cdots,j_k)(0\leq l\leq \mu_2-1)$; and so forth.

For example, if (4) has k distinct roots, then

$$D(j_1,\cdots,j_k)=\det(z_s^{j_r})_{r,s=1}^k.$$

There is an ambiguity in Definition 1, since the m zeros of P(z) may be numbered in any order; however, our results involve ratios of the form

$$D(j_1,\cdots,j_k)/D(j'_1,\cdots,j'_k),$$

which are left invariant if z_1, \dots, z_m are permuted. Because of (2), $z_i \neq 0$ $(1 \leq j \leq m)$,

so $D(j_1, \dots, j_k)$ exists for all j_1, \dots, j_k . It can be shown that

$$D(0, 1, \dots, k-1) = K \prod_{1 \le i < j \le m} (z_j - z_i)^{r_{ij}}$$

where K > 0 and the r_{ij} 's are positive integers. If m = k, then $D(0, 1, \dots, k-1)$ is the Vandermonde determinant, so $K = r_{ij} = 1$.

LEMMA 1. Suppose $1 \le l \le k$ and $j_1, \dots, j_{l-1}, j_{l+1}, \dots, j_k$ are fixed integers. Then the sequence

(9)
$$e_r = D(j_1, \dots, j_{l-1}, r, j_{l+1}, \dots, j_k), \quad -\infty < r < \infty$$

satisfies the difference equation

(10)
$$\sum_{\nu=-q}^{p} \phi_{\nu} e_{\nu+r} = 0.$$

Proof. Because of Definition 1, expanding the determinant in (9) in terms of cofactors of its *l*th row yields

(11)
$$e_r = \sum_{j=1}^m \sum_{i=0}^{\mu_j - 1} a_{ij}(r)^{(i)} z_j^{r-i},$$

where

$$(r)^{(0)} = 1,$$
 $(r)^{(i)} = r(r-1) \cdot \cdot \cdot (r-i+1), \quad i \ge 1,$

and the a_{ij} 's are constants. But if $1 \le j \le m$ and $0 \le i \le \mu_j - 1$, then

$$\sum_{\nu=-q}^{p} \phi_{\nu}(\nu+r)^{(i)} z_{j}^{\nu+r-i} = 0, \quad -\infty < r < \infty,$$

since z_j is a zero of $z^{r-q}P(z)$, with multiplicity μ_p for every r. This and (11) imply (10). LEMMA 2 a) The sequence $\{\alpha_r\}$ defined by

(12) (a)
$$\alpha_r = 0$$
, $r < 0$,
(b) $\alpha_r = \frac{1}{\phi_{-a}} \frac{D(-r, 1, \dots, k-1)}{D(0, 1, \dots, k-1)}$, $r \ge -k+1$,

satisfies

(13)
$$\sum_{\nu=-q}^{p} \phi_{\nu} \alpha_{j-q-\nu} = \delta_{j0}, \quad -\infty < j < \infty.$$

b) The sequence $\{\beta_i\}$ defined by

(14) (a)
$$\beta_r = 0$$
, $r < 0$,
(b) $\beta_r = \frac{1}{\phi_p} \frac{D(0, 1, \dots, k-2, r+k-1)}{D(0, 1, \dots, k-1)}$, $r \ge -k+1$,

satisfies

(15)
$$\sum_{\nu=-a}^{p} \phi_{\nu} \beta_{j-p+\nu} = \delta_{j0}, \quad -\infty < j < \infty.$$

(*Note.* The definitions (12) and (14) are redundant, but consistent, for $-k+1 \le j \le -1$. They are stated this way for convenience.)

Proof. (a) If j < 0, then (12a) implies (13). If j = 0, then (13) reduces to

$$\phi_{-q}\alpha_0=1,$$

again because of (12a). This is consistent with (12b) with r = 0. If $j \ge 1$, then (12b) and Lemma 1 imply (13).

(b) Similar proof.

Notice that the sequences $\{\alpha_r\}$ and $\{\beta_r\}$ can be computed recursively from (13) and (15), or explicitly from (12) and (14).

Lemma 2 implies (5), (6), (7), and (8). Therefore, (12) provides an explicit formula for T_n^{-1} if q = 0 (T_n is lower triangular), while (14) serves the same purpose if p = 0 (T_n is upper triangular). Of course, the inversion of triangular Toeplitz matrices—banded or not—is very simple, as was observed in [15]. We assume henceforth that

$$(16) p \ge 1 and q \ge 1.$$

3. The main results. The next theorem follows from a result in [16] concerning the eigenvalues of Toeplitz band matrices; however, since the proof in [16] utilizes a more involved argument than is needed here, it is convenient to prove Theorem 1 directly.

THEOREM 1. If (2) and (16) hold, then T_n is invertible if and only if

(17)
$$D(0,1,\dots,q-1,n+q+1,\dots,n+k)\neq 0.$$

Proof. We prove the equivalent assertion that the system

(18)
$$T'_n X = 0 \qquad ('= transpose)$$

has a nontrivial solution $X = \operatorname{col}[x_0, \dots, x_n]$ if and only if

(19)
$$D(0, 1, \dots, q-1, n+q+1, \dots, n+k) = 0.$$

Easy manipulations show that (18) holds if and only if the finite sequence

$$x_{-q}, \cdots, x_{-1}, x_0, \cdots, x_n, x_{n+1}, \cdots, x_{n+p}$$

satisfies the boundary value problem

(20)
$$\sum_{\nu=-q}^{p} \phi_{\nu} x_{\nu+r} = 0, \qquad 0 \le r \le n,$$
(20)
$$(b) x_{r} = 0 \quad \text{if } -q \le r \le -1 \text{ or } n+1 \le r \le n+p.$$

However, because of Assumption A and the fact that $z_j \neq 0$ $(1 \leq j \leq m)$, the elementary theory of constant coefficient difference equations implies that a solution of (20a) must be of the form

(21)
$$x_r = \sum_{j=1}^m \sum_{i=0}^{\mu_j-1} a_{ij} (q+r)^{(i)} z_j^{q+r-i}, \qquad -q \le r \le n+p,$$

where

$$A = \operatorname{col} [a_{01}, \dots, a_{\mu_1-1,1}, \dots, a_{0m}, \dots, a_{\mu_m-1,m}]$$

is a constant vector. On recalling Definition 1, it can be seen that (21) is consistent with (20b) if and only if A satisfies the $k \times k$ system

$$(22) HA = 0,$$

where

$$\det H = D(0, 1, \dots, q-1, n+q+1, \dots, n+k).$$

Therefore (22) has a nontrivial solution, and the same is true of (18), if and only if (19) holds. This completes the proof.

Henceforth, we assume that (17) holds.

DEFINITION 2. Let

$$U_n = \{0, 1, \dots, q-1, n+q+1, \dots, n+k\}.$$

If $\mu \in U_n$ and l is an arbitrary integer, define

$$a_n(\mu | l) = \frac{D(j_0, \dots, j_{q-1}, j_{n+q+1}, \dots, j_{n+k})}{D(0, 1, \dots, q-1, n+q+1, \dots, n+k)},$$

where

$$j_i = \begin{cases} i & \text{if } i \in U_n - \{\mu\}, \\ l & \text{if } i = \mu. \end{cases}$$

For example,

$$a_n(0|l) = \frac{D(l, 1, \dots, q-1, n+q+1, \dots, n+k)}{D(0, 1, \dots, q-1, n+q+1, \dots, n+k)}$$

and

$$a_n(n+q+1|l) = \frac{D(0,1,\cdots,q-1,l,n+q+2,\cdots,n+k)}{D(0,1,\cdots,q-1,n+q+1,\cdots,n+k)}.$$

Lemma 1 and Definition 2 imply the following lemma.

LEMMA 3. If μ is a fixed integer in U_n , then

$$\sum_{\nu=-q}^{p} \phi_{\nu} a_{n}(\mu | \nu+r) = 0, \quad -\infty < r < \infty,$$

and

$$a_n(\mu|r) = \delta_{\mu r}, \quad r \in U_n;$$

i.e., $e_r = a_n(\mu | r)$ is the unique solution of (10) which satisfies the boundary conditions

$$e_r = \delta_{\mu r}$$
, $0 \le r \le q - 1$, $n + q + 1 \le r \le n + k$.

The uniqueness assertion of Lemma 3 follows from (17), as can be seen from the proof of Theorem 1, since the difference of two solutions would satisfy (20).

The next two theorems give explicit formulas for b_{rsn} , the general element of T_n^{-1} . The formula in Theorem 2 is more convenient if q < p, while the formula in Theorem 3 is more convenient if p > q.

THEOREM 2. The general element b_{rsn} of $B_n = T_n^{-1}$ is given by

(23)
$$b_{rsn} = \alpha_{r-s-q} - \sum_{l=0}^{q-1} \alpha_{r-l} a_n(l|q+s),$$

where $\{\alpha_r\}$ is as in (12).

Proof. The condition $B_n T_n = I_n$ is equivalent to

$$\sum_{j=0}^{n} b_{rjn} \phi_{j-s} = \delta_{rs}, \qquad 0 \le r, s \le n.$$

which can be rewritten as

(24)
$$\sum_{j=-q}^{n+p} b_{rjn}\phi_{j-s} = \delta_{rs}, \qquad 0 \leq r, s \leq n,$$

if we define

(25)
$$b_{rsn} = 0 \quad \text{when } -q \le s \le -1 \text{ or } n+1 \le s \le n+p.$$

Shifting the index of summation in (24) and recalling (1) yields

(26)
$$\sum_{\nu=-q}^{p} \phi_{\nu} b_{r,\nu+s,n} = \delta_{rs}, \qquad 0 \le r, s \le n.$$

Now let

$$(27) b_{rsn} = \alpha_{r-s-q} + u_{rsn}, 0 \le r \le n, -q \le s \le n+p,$$

where u_{rsn} is to be determined. From (13) with j = r - s,

$$\sum_{\nu=-q}^{p} \phi_{\nu} \alpha_{r-s-q-\nu} = \delta_{0,r-s} = \delta_{rs}, \qquad 0 \le r, s \le n;$$

hence, substituting (27) into (26) and recalling (25) shows that for each r in $\{0, \dots, n\}$, the sequence $\{u_{rsn}\}_{s=-q}^{n+p}$ satisfies the difference equation

$$\sum_{\nu=-q}^{p} \phi_{\nu} u_{r,\nu+s,n} = 0, \qquad 0 \leq s \leq n,$$

and the boundary conditions

$$u_{rsn} = -\alpha_{r-s-q} = 0,$$
 $n+1 \le s \le n+p$ (cf. (12a)),

$$u_{rsn} = -\alpha_{r-s-q}, \qquad -q \le s \le -1.$$

This and Lemma 3 imply that

$$u_{rsn} = -\sum_{l=0}^{q-1} \alpha_{r-l} a_n(l|q+s),$$

which, with (27), implies (23).

THEOREM 3. The general element b_{rsn} of $B_n = T_n^{-1}$ is given by

(28)
$$b_{rsn} = \beta_{s-r-p} - \sum_{l=0}^{p-1} \beta_{s-p+l+1} a_n (n+q+l+1 \mid n+q-r),$$

with $\{\beta_i\}$ as defined by (14).

Proof. The condition $T_n B_n = I_n$ is equivalent to

$$\sum_{j=0}^{n} \phi_{r-j} b_{jsn} = \delta_{rs}, \qquad 0 \le r, s \le n,$$

which can be rewritten as

(29)
$$\sum_{j=-p}^{n+q} \phi_{r-j} b_{jsn} = \delta_{rs}, \qquad 0 \le r, s \le n,$$

if we define

(30)
$$b_{rsn} = 0 \quad \text{when } -p \le r \le -1 \text{ or } n+1 \le r \le n+q.$$

Changing the index of summation in (29) and recalling (1) yields

(31)
$$\sum_{\nu=-q}^{p} \phi_{\nu} b_{r-\nu,sn} = \delta_{rs}, \qquad 0 \leq r, s \leq n.$$

Now let

$$(32) b_{rsn} = \beta_{s-r-p} + v_{rsn},$$

where v_{rsn} is to be determined. From (15) with j = s - r,

$$\sum_{\nu=-q}^{p} \phi_{\nu} \beta_{s-r-p+\nu} = \delta_{rs}, \qquad 0 \le r, s \le n;$$

hence, substituting (32) into (31) and recalling (30) shows that for each s in $\{0, \dots, n\}$, the sequence $\{v_{rsn}\}_{r=-p}^{n+q}$ satisfies the difference equation

$$\sum_{\nu=-q}^{p} \phi_{\nu} v_{r-\nu,sn} = 0, \qquad 0 \le r \le n,$$

and the boundary conditions

$$v_{rsn} = -\beta_{s-r-p} = 0,$$
 $n+1 \le r \le n+q,$
 $v_{rsn} = -\beta_{s-r-p},$ $-p \le r \le -1.$

This and Lemma 3 imply that

$$v_{rsn} = -\sum_{l=0}^{p-1} \beta_{s-p+l+1} a_n (n+q+l+1|n+q-r);$$

which, with (32), implies (28).

The next theorem provides explicit formulas for the solution of (3) when T_n is invertible. Here we write

$$X = \operatorname{col}[x_0, \dots, x_n]$$
 and $Y = \operatorname{col}[y_0, \dots, y_n]$

and adopt the convention that

$$\sum_{\nu=0}^{\nu} = 0 \quad \text{if } \nu < \mu.$$

THEOREM 4. If T_n is invertible, then the solution of (3) is given by

(33)
$$x_r = \sum_{s=0}^{r-q} \alpha_{r-s-q} y_s - \sum_{l=0}^{q-1} \alpha_{r-l} \sum_{s=0}^{n} y_s a_n(l|q+s), \qquad 0 \le r \le n,$$

and by

(34)
$$x_r = \sum_{s=r+p}^{n} \beta_{s-r-p} y_s - \sum_{l=0}^{p-1} \left(\sum_{s=0}^{n} \beta_{s-p+l+1} y_s \right) a_n (n+q+l+1 \mid n+q-r), \quad 0 \le r \le n.$$

Proof. Since

$$x_r = \sum_{s=0}^n b_{rsn} y_s, \qquad 0 \le r \le n,$$

(23) implies (33) and (28) implies (34).

Since convolutions can be implemented efficiently by means of fast Fourier transforms, (33) provides an efficient computational method for solving (3). The quantities

$$M_l = \sum_{s=0}^n y_s a_n(l|q+s), \qquad 0 \le l \le q-1$$

(each of which can be expressed as the ratio of two $k \times k$ determinants) would be computed first. Then, from (33),

$$x_r = -\sum_{l=0}^r M_l \alpha_{r-l}, \qquad 0 \le r \le q-1,$$

and

$$x_r = \sum_{s=0}^{r-q} \alpha_{r-s-q} y_s - \sum_{l=0}^{q-1} M_l \alpha_{r-l}, \quad q \le r \le n.$$

It is easily verified that (33) and (34) remain valid if p = 0 or q = 0.

The next lemma follows trivially from the last four equations of [13].

LEMMA 4. Suppose T_n is an arbitrary (not necessarily banded) Toeplitz matrix, with inverse $T_n^{-1} = (b_{rsn})_{r,s=0}^n$, where

$$(35) b_{00n} \neq 0.$$

Then the elements $b_{rsn}(1 \le r, s \le n)$ are determined in terms of $b_{r0n}(0 \le r \le n)$ and $b_{0sn}(0 \le s \le n)$ by the recursion formula

(36)
$$b_{rsn} = b_{r-1,s-1,n} + (b_{00n})^{-1} (b_{r0n}b_{0sn} - b_{n-s+1,0,n}b_{0,n-r+1,n}), \quad 1 \le r, s \le n.$$

Since $b_{00n} = \det T_{n-1}/\det T_n$, (35) implies that T_{n-1} is also invertible. Since T_n^{-1} is persymmetric (i.e., symmetric about its secondary diagonal), it is only necessary to use (36) for $r+s \le n$, and then take

$$b_{rsn} = b_{n-s,n-r,n},$$
 $1 \le r, s \le n, r+s > n.$

Lemma 4 was rediscovered and presented in a useful matrix form by Gohberg and Semencul [5]. In most applications (e.g., [3], [8], [13], [15], [16]), it has been coupled with recursive procedures for obtaining the elements of the zeroth row and column of T_n^{-1} ; however, these methods usually require that other matrices in the sequence $\{T_0, T_1, \cdots\}$ be nonsingular. Since Theorems 2 and 3 provide convenient explicit formulas for the zeroth row and column of T_n^{-1} , we can dispense with this additional assumption here. Thus, from (12) and (23),

(37)
$$b_{0sn} = -(\phi_{-q})^{-1} a_n(0|q+s), \qquad 0 \le s \le n,$$

while from (14) and (28),

(38)
$$b_{r0n} = -(\phi_n)^{-1} a_n (n+k|n+q-r), \qquad 0 \le r \le n.$$

If evaluating the $k \times k$ determinants in (37) is inconvenient, then it is only necessary to use (37) for $0 \le s \le p$; define

$$b_{0sn}=0, \qquad -q+1 \le s \le -1,$$

and compute recursively:

$$b_{0sn} = -(\phi_p)^{-1} \sum_{\nu=-q}^{p-1} \phi_{\nu} b_{0,\nu+s-p,n}, \qquad p+1 \le s \le n.$$

(See Lemma 3.) Similarly, we can use (38) for $0 \le r \le q$; define

$$b_{r0n}=0, \qquad -p+1 \le r \le -1,$$

and compute recursively:

$$b_{r0n} = -(\phi_{-q})^{-1} \sum_{\nu=-p}^{q-1} \phi_{-\nu} b_{r+\nu-q,0,n}, \qquad q+1 \le r \le n.$$

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