

Linear differential systems with coefficient matrices that commute with a spectrally separated matrix function in

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*Asymptotic preconditioning of linear homogeneous systems of differential equations, Linear Algebra Appl. 434 (2011), 1631-1637.*

*R is a real or complex  $n \times n$  matrix-valued function on an interval  $\mathcal{I}$  that can be written as*

$$R = P \mathbf{D} P^{-1}$$

*where  $n_1 + \dots + n_k = n$ ,*

$$P = [ P_1 \quad P_2 \quad \dots \quad P_k ], \quad P_\ell \in \mathbb{C}_1^{n \times n_\ell}(\mathcal{I}), \quad 1 \leq \ell \leq k,$$

$$\mathbf{D} = \text{diag}(\mu_1 I_{n_1}, \mu_2 I_{n_2}, \dots, \mu_k I_{n_k})$$

*and  $\mu_1(t), \dots, \mu_k(t)$  are distinct for every  $t \in \mathcal{I}$ . Thus,  $R$  is diagonalizable and has  $k$  distinct eigenvalues for all  $t \in \mathcal{I}$ , with constant multiplicities  $n_1, \dots, n_k$ .*

*Our objective: To consider differential systems  $x' = A(t)x$  where  $A \in \mathbb{C}_0^{n \times n}(\mathcal{I})$  and  $RA = AR$  on  $\mathcal{I}$ .*

*Later we'll add another condition on  $R$ . First, what are the consequences of the commutativity?*

We can write

$$P^{-1} = \begin{bmatrix} \widehat{P}_1 \\ \widehat{P}_2 \\ \vdots \\ \widehat{P}_k \end{bmatrix} \quad \text{where} \quad \widehat{P}_r P_s = \delta_{rs} I_{n_r}, \quad 1 \leq r, s \leq k.$$

**Theorem 1**  $RA = AR$  on  $\mathcal{J}$  if and only if

$$A = P \operatorname{diag}(F_1, \dots, F_k) P^{-1} = \sum_{\ell=1}^k P_\ell F_\ell \widehat{P}_\ell$$

with

$$F_\ell = \widehat{P}_\ell A P_\ell, \quad 1 \leq \ell \leq k.$$

PROOF. We can always write

$$A = P C P^{-1} = P \begin{bmatrix} C_{11} & C_{12} & \cdots & C_{1k} \\ C_{21} & C_{22} & \cdots & C_{2k} \\ \vdots & \vdots & \ddots & \vdots \\ C_{k1} & C_{k2} & \cdots & C_{kk} \end{bmatrix} P^{-1}$$

with  $C_{rs} \in \mathbb{C}^{n_r \times n_s}(\mathcal{J})$ . Just let  $C = P^{-1} A P$  and partition  $C$  into blocks. (This is purely conceptual; we don't really have to do it.) Then

$$\begin{aligned}
RA &= (PDP^{-1})(PCP^{-1}) = PDCP^{-1} \\
&= P \begin{bmatrix} \mu_1 C_{11} & \mu_1 C_{12} & \cdots & \mu_1 C_{1k} \\ \mu_2 C_{21} & \mu_2 C_{22} & \cdots & \mu_2 C_{2k} \\ \vdots & \vdots & \ddots & \vdots \\ \mu_k C_{k1} & \mu_k C_{k2} & \cdots & \mu_k C_{kk} \end{bmatrix} P^{-1}
\end{aligned}$$

and

$$\begin{aligned}
AR &= (PCP^{-1})(PDP^{-1}) = PCDP^{-1} \\
&= P \begin{bmatrix} \mu_1 C_{11} & \mu_2 C_{12} & \cdots & \mu_k C_{1k} \\ \mu_1 C_{21} & \mu_2 C_{22} & \cdots & \mu_k C_{2k} \\ \vdots & \vdots & \ddots & \vdots \\ \mu_1 C_{k1} & \mu_2 C_{k2} & \cdots & \mu_k C_{kk} \end{bmatrix} P^{-1}.
\end{aligned}$$

Hence  $RA = AR$  if and only if

$$\mu_r C_{rs} = \mu_s C_{rs}, \quad 1 \leq r, s \leq k. \quad (1)$$

Since  $\mu_r \neq \mu_s$  if  $r \neq s$ , (1) is equivalent to  $C_{rs} = 0$  if  $r \neq s$ ,  $1 \leq r, s \leq k$ . For better notation, write

$$C_{\ell\ell} = F_\ell \in \mathbb{C}^{n_\ell \times n_\ell} \quad \text{and} \quad \mathbf{F} = \text{diag}(F_1, F_2, \dots, F_k).$$

We have now shown that  $RA = AR$  on  $\mathcal{I}$  if and only if  $P^{-1}AP = \mathbf{F}$  or, equivalently,  $A = P\mathbf{F}P^{-1}$ ; i.e.,  $R$  and  $A$  have the same block diagonal form with respect to  $P$  (for all  $t \in \mathcal{I}$ ).

Now we want a formula for  $F_0, \dots, F_k$ . Since  $A = PFP^{-1}$ ,  $AP = PF$ ; i.e.,

$$\begin{bmatrix} AP_1 & AP_2 & \cdots & AP_k \end{bmatrix} = \begin{bmatrix} P_1F_1 & P_2F_2 & \cdots & P_kF_k \end{bmatrix},$$

so  $AP_\ell = P_\ell F_\ell$ ,  $1 \leq \ell \leq k$ . Since  $\widehat{P}_\ell P_\ell = I_{n_\ell}$ , it follows that  $F_\ell = \widehat{P}_\ell AP_\ell$ ,  $1 \leq \ell \leq k$ .  $\square$

*Example: (Variable block circulant system) If  $P$  is constant we can use this result to simplify the solution of  $x' = A(t)x$ . For example, consider the block circulant matrix function*

$$A = \begin{bmatrix} A_0 & A_1 & A_2 & \cdots & A_{k-2} & A_{k-1} \\ A_{k-1} & A_0 & A_1 & \cdots & A_{k-3} & A_{k-2} \\ A_{k-2} & A_{k-1} & A_0 & \cdots & A_{k-4} & A_{k-3} \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ A_1 & A_2 & A_3 & \cdots & A_{k-1} & A_0 \end{bmatrix} \in \mathbb{C}_0^{kd \times kd}(\mathcal{J})$$

with  $A_0, A_1, \dots, A_{k-1} \in \mathbb{C}_0^{d \times d}(\mathcal{J})$ . Then  $RA = AR$  if

$$R = \begin{bmatrix} 0 & I_d & 0 & \cdots & 0 & 0 \\ 0 & 0 & I_d & \cdots & 0 & 0 \\ 0 & 0 & 0 & \cdots & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & 0 & I_d \\ I_d & 0 & 0 & \cdots & 0 & 0 \end{bmatrix}$$

(replace  $A_1$  by  $I_d$ , all other  $A_\ell$ 's by  $0_{d \times d}$ ).

Denote  $\zeta = e^{2\pi i/k}$ . Then

$$R = P \operatorname{diag}(I_d, \zeta I_d, \zeta^2 I_d, \dots, \zeta^{k-1} I_d) P^{-1}$$

where  $P = [ P_1 \ P_2 \ \cdots \ P_k ]$  with

$$P_\ell = \frac{1}{\sqrt{k}} \begin{bmatrix} I_d \\ \zeta^{\ell-1} I_d \\ \zeta^{2(\ell-1)} I_d \\ \vdots \\ \zeta^{(k-1)(\ell-1)} I_d \end{bmatrix}, \quad 1 \leq \ell \leq k.$$

Therefore Theorem 1 implies that

$$A = P \operatorname{diag}(F_1, \dots, F_k) P^{-1} = \sum_{\ell=1}^k P_\ell F_\ell \widehat{P}_\ell$$

with

$$F_\ell = \widehat{P}_\ell A P_\ell = \frac{1}{k} \sum_{m=0}^{k-1} \zeta^{(\ell-1)m} A_m, \quad 1 \leq \ell \leq k,$$

(after some computation). Therefore,  $x' = A(t)x$  if and only if

$$x = \sum_{\ell=1}^k P_\ell y_\ell \quad \text{where} \quad y'_\ell = F_\ell(t) y_\ell, \quad 1 \leq \ell \leq k.$$

Therefore, the only way to understand  $x' = A(t)x$  (whatever we mean by this), is to understand the component systems  $y'_\ell = F_\ell(t)y_\ell$ ,  $1 \leq \ell \leq k$ . For example, if  $\mathcal{I} = [a, \infty)$  a standard theorem of Bôcher says that if

$$\int^{\infty} \|A(t)\| dt < \infty$$

then every nonzero solution of  $x' = A(t)x$  approaches a nonzero limit as  $t \rightarrow \infty$ , or, equivalently, if  $\xi \in \mathbb{C}^{kd}$  then  $x' = A(t)x$  has a unique solution  $x$  such that

$$\lim_{t \rightarrow \infty} x(t) = \xi.$$

This theorem is not directly applicable to  $x' = A(t)x$  if

$$\int^{\infty} \|F_\ell(t)\| dt = \infty$$

for some  $\ell \in \{1, \dots, k\}$ , which implies that

$$\int^{\infty} \|A(t)\| dt = \infty.$$

However, if

$$\mathcal{S} = \left\{ \ell \mid \int^{\infty} \|F_\ell(t)\| dt < \infty \right\} \neq \emptyset$$

and  $u_\ell \in \mathbb{C}^d$ ,  $\ell \in \mathcal{S}$ , then applying the theorem separately to  $y'_\ell = F_\ell(t)y_\ell$ ,  $\ell \in \mathcal{S}$ , shows that  $x' = A(t)x$  has a unique solution

$$x = \sum_{\ell \in \mathcal{S}} P_\ell y_\ell \quad \text{such that} \quad \lim_{t \rightarrow \infty} y_\ell(t) = u_\ell. \quad \ell \in \mathcal{S},$$

To carry this over to the case where  $P$  is a variable matrix, we need another assumption:

$$P' = P \operatorname{diag}(U_1, U_2, \dots, U_k) \quad \text{with} \quad U_\ell \in \mathbb{C}_0^{n_\ell \times n_\ell};$$

i.e.,

$$P'_\ell = P_\ell U_\ell \quad \text{with} \quad U_\ell, \quad 1 \leq \ell \leq k.$$

Thus, for each  $t$ ,  $P'_\ell(t)$  is in the column space of  $P(t)$  (the  $\mu_k(t)$ -eigenspace of  $R(t)$ ). In this case we say that  $R$  is spectrally separated. (I'm open to suggestions of better terminology.)



To solve

$$x' = A(t)x + f(t), \quad x(t_0) = x_0,$$

write

$$x_0 = \sum_{\ell=1}^k P_{\ell} y_{0\ell} \quad \text{with} \quad y_{0\ell} = \widehat{P}_{\ell} x_0 \in \mathbb{C}^{n_{\ell}}$$

and

$$f = \sum_{\ell=1}^k P_{\ell} h_{\ell} \quad \text{with} \quad h_{\ell} = \widehat{P}_{\ell} f \in \mathbb{C}^{n_{\ell}}(\mathcal{I}),$$

and solve the  $k$  initial value problems

$$y_{\ell}' = (F_{\ell}(t) - U_{\ell}(t))y_{\ell} + h_{\ell}(t), \quad y_{\ell}(t_0) = y_{0\ell}, \quad 1 \leq \ell \leq k.$$

Recall that  $A = P\mathbf{F}P^{-1}$  where  $\mathbf{F} = \text{diag}(F_1, \dots, F_k)$ . Denote  $\mathbf{U} = \text{diag}(U_1, \dots, U_k)$ , so  $P' = P\mathbf{U}$ . To solve  $x' = A(t)x$ , write

$$x = Py = \begin{bmatrix} P_1 & P_2 & \cdots & P_k \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_k \end{bmatrix} \quad \text{with } y_\ell \in \mathbb{C}_0^{n_\ell}(\mathcal{I}).$$

Since

$$Ax = (P\mathbf{F}P^{-1})(Py) = PFy$$

and

$$x' = Py' + P'y = Py' + P\mathbf{U}y = P(y' + \mathbf{U}y)$$

it follows that  $x' = A(t)x$  if and only if

$$y' + \mathbf{U}y = \mathbf{F}y \iff y' = (\mathbf{F} - \mathbf{U})y,$$

which is equivalent to

$$y'_\ell = (F_\ell(t) - U_\ell(t))y, \quad 1 \leq \ell \leq k.$$

Recall that a fundamental matrix for  $x' = A(t)x$  is an invertible  $n \times n$  matrix function  $X$  such that  $X' = A(t)X$ .

**Theorem 2** If  $RA = AR$  on  $\mathcal{I}$  and  $\mathbf{Y} = \bigoplus_{\ell=1}^k Y_{\ell}$  where  $Y_1, Y_2, \dots, Y_k$  are fundamental matrices for the systems  $y'_{\ell} = (F_{\ell}(t) - U_{\ell}(t))y_{\ell}$ ,  $1 \leq \ell \leq k$ , then  $X = P\mathbf{Y}$  is a fundamental matrix for  $x' = A(t)x$ . Moreover, if  $t_0 \in \mathcal{I}$  and  $x_0 \in \mathbb{C}^n$  then the solution of the initial value problem  $x' = A(t)x$ ,  $x(t_0) = x_0$ , is

$$x(t) = \sum_{\ell=1}^k P_{\ell}(t)Y_{\ell}(t)Y_{\ell}^{-1}(t_0)y_{0\ell} \text{ where } y_{0\ell} = \widehat{P}_{\ell}(t_0)x_0,$$

$1 \leq \ell \leq k$ . The general solution of  $x' = A(t)x$  is

$$x(t) = \sum_{\ell=1}^k P_{\ell}(t)Y_{\ell}(t)c_{\ell} \text{ where } c_{\ell} \in \mathbb{C}^{n_{\ell}}, \quad 1 \leq \ell \leq k.$$

**Theorem 3** Suppose  $A \in \mathbb{C}^{n \times n}(\mathcal{I})$  is  $R$ -symmetric,  $f \in \mathbb{C}^n(\mathcal{I})$ , and  $t_0 \in \mathcal{I}$ . Let  $Y_1, Y_2, \dots, Y_k$  be fundamental matrices for the systems  $y'_\ell = (F_\ell(t) - U_\ell(t))y_\ell$ ,  $1 \leq \ell \leq k$ . Then the solution of

$$x' = A(t)x + f(t), \quad x(t_0) = x_0,$$

is

$$x(t) = \sum_{\ell=1}^k P_\ell(t) Y_\ell(t) \left( Y_\ell^{-1}(t_0) y_{0\ell} + \int_{t_0}^t Y_\ell^{-1}(\tau) h_\ell(\tau) d\tau \right),$$

where

$$y_{0\ell} = \widehat{P}_\ell(t_0)x_0 \quad \text{and} \quad h_\ell = \widehat{P}_\ell f, \quad 1 \leq \ell \leq k.$$

**Theorem 4** Suppose  $A \in \mathbb{C}^{n \times n}(\mathcal{I})$ . Let

$$\mathcal{S}_A = \{x \in \mathbb{C}_1^{n \times n}(\mathcal{I}) \mid x'(t) = A(t)x(t), t \in \mathcal{I}\}$$

(solution set of  $x' = A(t)x$ ) and

$$\mathcal{E}_R = \bigcup_{\ell=1}^k \{x \in \mathbb{C}_1^{n \times n}(\mathcal{I}) \mid R(t)x(t) = \mu_\ell(t)x(t), t \in \mathcal{I}\}$$

(union of the time-varying eigenspaces of  $R$ ). Then  $A$  is  $R$ -symmetric if and only if  $\mathcal{S}_A$  has a basis in  $\mathcal{E}_R$ .

PROOF. If  $RA = AR$  on  $\mathcal{I}$  then the general solution of  $x' = A(t)x$  is  $x = \sum_{\ell=1}^k P_\ell y_\ell$ . Since  $RP_\ell = \mu_\ell P_\ell$ ,  $1 \leq \ell \leq k$ . This implies necessity.

For sufficiency, if  $\mathcal{S}_A$  has a basis in  $\mathcal{E}_R$  then  $x' = Ax$  has a fundamental matrix of the form

$$X = P\mathbf{Y} = [ P_1 \ P_2 \ \cdots \ P_k ] \text{diag}(Y_1, Y_2, \dots, Y_k),$$

where

$$Y_\ell \text{ and } Y_\ell^{-1} \in \mathbb{C}_1^{n_\ell \times n_\ell}(\mathcal{J}), \quad 1 \leq \ell \leq k.$$

Therefore  $AP\mathbf{Y} = (P\mathbf{Y})' = P'\mathbf{Y} + P\mathbf{Y}'$ , so

$$\begin{aligned} A &= (P'\mathbf{Y} + P\mathbf{Y}')\mathbf{Y}^{-1}P^{-1} = P'P^{-1} + P(\mathbf{Y}'\mathbf{Y}^{-1})P^{-1} \\ &= P(P^{-1}P')P^{-1} + P(\mathbf{Y}'\mathbf{Y}^{-1})P^{-1} \\ &= P(\mathbf{U} + \mathbf{Y}'\mathbf{Y}^{-1})P^{-1} = P\mathbf{F}P^{-1} \end{aligned}$$

(since  $P' = PU$ ), with

$$\mathbf{F} = \mathbf{U} + \mathbf{Y}'\mathbf{Y}^{-1} = \bigoplus_{\ell=0}^{k-1} (U_\ell + Y'_\ell Y_\ell^{-1}).$$

Hence  $RA = AR$  on  $\mathcal{J}$ , by Theorem 1.

*Closing comment on  $x' = A(t)x$ :*

*Suppose  $\mathcal{I} = [a, \infty)$  and  $RA = AR$  on  $\mathcal{I}$ . Since the general solution of  $x' = A(t)x$  is of the form*

$$y = \sum_{\ell=1}^k P_{\ell} y_{\ell} \quad \text{where} \quad y'_{\ell} = (F_{\ell}(t) - U_{\ell}(t))y_{\ell},$$

*it seems that the best (only?) way to study the asymptotic behavior of solutions of  $x' = A(t)x$  is to study the separate behaviors of the components  $y_1, \dots, y_k$ .*

*For example, Bôcher's theorem implies the following result.*

**Theorem** *Suppose that  $RA = AR$  on  $\mathcal{I}$  and  $\int^{\infty} \|F_{\ell} - U_{\ell}\| dt < \infty$  for all  $\ell$  in a nonempty subset  $\mathcal{S}$  of  $\{1, \dots, k\}$ . For each  $\ell \in \mathcal{S}$  let  $u_{\ell} \in \mathbb{C}^{n_{\ell}}$  be given. Then  $x' = A(t)x$  has a unique solution  $x = \sum_{\ell \in \mathcal{S}} P_{\ell} y_{\ell}$  such that  $\lim_{t \rightarrow \infty} y_{\ell}(t) = u_{\ell}$ ,  $\ell \in \mathcal{S}$ .*

## DISCRETE FORMULATION

Let  $\mathbb{Z}_+$  be the set of nonnegative integers and consider linear systems of difference equations

$$x_{t+1} = (I + A_t)x_t, \quad t \in \mathbb{Z}_+, \quad x_0 = \xi,$$

where  $I + A_t \in \mathbb{C}^{n \times n}$  is invertible for all  $t \geq 0$ . Let

$$\mathbb{P}_t = [ P_{1t} \quad P_{2t} \quad \cdots \quad P_{kt} ] \quad \text{with} \quad \mathbb{P}_t^{-1} = \begin{bmatrix} \widehat{P}_{1t} \\ \widehat{P}_{2t} \\ \vdots \\ \widehat{P}_{kt} \end{bmatrix},$$

where  $P_{\ell t} \in \mathbb{C}^{n \times n_\ell}(\mathbb{Z}_+)$ ,  $\widehat{P}_{\ell t} \in \mathbb{C}^{n_\ell \times n}(\mathbb{Z}_+)$ ,  
and  $\widehat{P}_{\ell t} P_{mt} = \delta_{\ell m} I_{n_\ell}$ ,  $1 \leq \ell, m \leq k$ ,  $t \in \mathbb{Z}_+$ . Let

$$R_t = \mathbb{P}_t \text{diag}(\mu_{1t} I_{n_1}, \dots, \mu_{kt} I_{n_k}) \mathbb{P}_t^{-1},$$

where  $\mu_{1t}, \dots, \mu_{kt}$  are distinct for  $t \in \mathbb{Z}_+$ . Finally, let  $\mathbb{P}_{t+1} = \mathbb{P}_t(\mathbf{I} + \mathbf{U}_t)$ , where  $\mathbf{U}_t = \text{diag}(U_{1t}, \dots, U_{kt})$  with  $U_{\ell t} \in \mathbb{C}^{n_\ell \times n_\ell}(\mathbb{Z}_+)$ ,  $1 \leq \ell \leq k$ , and  $I + \mathbf{U}_t$  invertible for all  $t \in \mathbb{Z}_+$ .



**Theorem 5**  $R_t A_t = A_t R_t$  for all  $t \in \mathbb{Z}_+$  if and only if

$$A_t = \mathbb{P}_t \mathbf{F}_t \mathbb{P}_t^{-1} = \sum_{\ell=0}^{k-1} P_{\ell t} F_{\ell t} \widehat{P}_{\ell t} \quad (2)$$

with

$$F_{\ell t} = \widehat{P}_{\ell t} A_t P_{\ell t} \in \mathbb{C}^{n_\ell \times n_\ell}(\mathbb{Z}_+), \quad 1 \leq \ell \leq k, \quad t \in \mathbb{Z}_+.$$

Now suppose  $RA = AR$  on  $\mathcal{J}$  and want to solve

$$x_{t+1} = (I + A_t)x_t, \quad t > 0. \quad (3)$$

Write  $x_t = P_t y_t = \sum_{\ell=1}^k P_{\ell t} y_{\ell t}$ . Then

$$x_{t+1} = \sum_{\ell=1}^k P_{\ell, t+1} y_{\ell, t+1} = \sum_{\ell=1}^k P_{\ell t} (I_{n_\ell} + U_{\ell t}) y_{\ell, t+1}$$

and

$$\begin{aligned} (I + A_t)x_t &= \left( \sum_{\ell=1}^k P_{\ell t} (I_{n_\ell} + F_{\ell t}) \hat{P}_{\ell t} \right) \left( \sum_{m=1}^k P_{m t} y_{m t} \right) \\ &= \sum_{\ell=1}^k P_{\ell t} (I_{n_\ell} + F_{\ell t}) y_{\ell t}. \end{aligned}$$

Therefore (3) holds if only if

$$(I_{n_\ell} + U_{\ell t}) y_{\ell, t+1} = (I_{n_\ell} + F_{\ell t}) y_{\ell t}, \quad 1 \leq \ell \leq k, \quad t \in \mathbb{Z}_+,$$

or, equivalently,

$$y_{\ell, t+1} = (I_{n_\ell} + U_{\ell t})^{-1} (I_{n_\ell} + F_{\ell t}) y_{\ell t}, \quad 1 \leq \ell \leq k, \quad t \in \mathbb{Z}_+.$$

**Theorem 6** Suppose  $R_t A_t = A_t R_t$  for all  $t \in \mathbb{Z}_+$  and let

$$Q_{\ell t} = \mathbb{P}_{\ell t} \prod_{j=1}^{t-1} (I_{n_\ell} + U_{\ell j})^{-1} (I_{n_\ell} + F_{\ell j}), \quad t \in \mathbb{Z}_+, \quad Q_{\ell 0} = I_{n_\ell},$$

$1 \leq \ell \leq k$  Then

$$X_t = \begin{bmatrix} Q_{1t} & Q_{2t} & \cdots & Q_{kt} \end{bmatrix} \quad t > 0, \quad X_0 = I$$

is a fundamental matrix for the system

$$x_{t+1} = (I + A_t)x_t, \quad t \in \mathbb{Z}_+.$$

The discrete analog of Bôcher's theorem can be adapted to prove the following theorem.

**Theorem 7** Suppose  $R_t A_t = A_t R_t$  for all  $t \in \mathbb{Z}_+$  and

$$\sum_{t=0}^{\infty} \|(I_{n_\ell} + U_{\ell t})^{-1}(I + F_{\ell t}) - I_{n_\ell}\| < \infty$$

for all  $\ell$  in a nonempty subset  $\mathcal{S}$  of  $\{1, \dots, k\}$ . For each  $\ell \in \mathcal{S}$  let  $u_\ell$  be a given vector in  $\mathbb{C}^{n_\ell}$ . Then the system  $x_{t+1} = (I + A_t)x_t$  has a unique solution

$$x_t = \sum_{\ell \in \mathcal{S}} P_{\ell t} y_{\ell t} \quad \text{such that} \quad \lim_{t \rightarrow \infty} y_{\ell t} = u_\ell, \quad \ell \in \mathcal{S}.$$

## AN INTERESTING QUESTION

Consider

$$x' = A(t)x, \quad t > t_0, \quad (4)$$

where  $A \in \mathbb{C}^{n \times n}[t_0, \infty)$  (continuous) but has no particular structure. A system like this is “nice” if it has linear asymptotic equilibrium (every nontrivial solution approaches a nonzero limit), which is true, for example, if  $\int^{\infty} \|A(t)\| dt < \infty$ . However, suppose that  $\int^{\infty} \|A(t)\| dt = \infty$ . In this case it seems reasonable to look for a continuously differentiable and invertible matrix  $P = P(t)$  such that every nontrivial solution of (1) can be written as  $x = Py$ , where  $y$  approaches a nonzero limit as  $t \rightarrow \infty$ . In this case I'd like to say that  $P$  is a preconditioner for (4).

An easy sufficient (but not necessary) condition: Since  $x' = Py' + P'y$  and  $Ax = APy$ ,  $x' = Ax$  if and only if  $u' = P^{-1}(AP - P')$ . Hence  $P$  is a preconditioner for (1) if

$$\int^{\infty} \|P^{-1}(AP - P')\| dt < \infty.$$

*Some other definitions that can be extended in this way:*

**Definition 1** Let  $I = [a, \infty)$ ,  $A \in \mathbb{C}_0^{n \times n}(I)$ , and let  $\mathcal{S}_a$  be the solution set of (4). Then:

**(a)** Eqn. (4) is stable if there is a constant  $M$  such that  $\|x(t)\| \leq M \|x(a)\|$  for all  $x \in \mathcal{S}_A$ .

**(b)** Eqn. (4) is strictly stable if there is a constant  $M$  such that  $\|x(t)\| \leq M \|x(\tau)\|$  for all  $x \in \mathcal{S}_A$  and  $t, \tau \geq a$ .

**(c)**  $x' = A(t)x$  is uniformly stable if there is a constant  $M$  such that  $\|x(t)\| \leq M \|x(\tau)\|$  for all  $x \in \mathcal{S}_A$  and  $t \geq \tau \geq a \in I$ .

**(d)** Eqn. (4) is uniformly asymptotically stable if there are constants  $M$  and  $\nu > 0$  such that  $\|x(t)\| \leq M \|x(\tau)\| e^{-\nu(t-\tau)}$  for all  $x \in \mathcal{S}_A$  and  $t \geq \tau \geq a$ .

**(e)** Eqn. (4) has linear asymptotic equilibrium if every non-trivial solution of  $x' = A(t)x$  approaches a nonzero constant vector as  $t \rightarrow \infty$ .

*Definitions (c) and (d) can be combined in the following definition, which may be new. Let  $\rho$  be continuous and positive on  $\{(t, \tau) \mid t \geq \tau \geq a\}$  and suppose that*

$$\rho(t, t) = 1 \text{ and } \rho(t, \tau) \leq \rho(t, s)\rho(s, \tau) \text{ if } t \geq s \geq \tau \geq a.$$

*We say that (4) is  $\rho$ -stable if there is a constant  $M$  such that*

$$\|x(t)\| \leq \frac{\|x(\tau)\|}{\rho(s, t)} \text{ for all } x \in \mathcal{S}_A \text{ and } t \geq \tau \geq a.$$

**Definition 2** Suppose  $P \in \mathbb{C}_1^{n \times n}(\mathcal{J})$ . Then:

(a) Eqn. (4) is stable relative to  $P$  if there is a constant  $M$  such that

$$\|P^{-1}(t)x(t)\| \leq M \|P^{-1}(a)x(a)\|$$

(b) Eqn. (4) is strictly stable relative to  $P$  if there is a constant  $M$  such that

$$\|P^{-1}(t)x(t)\| \leq M \|P^{-1}(\tau)x(\tau)\| \quad \text{for all } x \in \mathcal{S}_A$$

and  $t, \tau \geq a$ .

(c) Eqn. (4) is  $\rho$ -stable relative to  $P$  if there is a constant  $K$  such that

$$\|P^{-1}(t)x(t)\| \leq M \frac{\|P^{-1}(\tau)x(\tau)\|}{\rho(t, \tau)} \quad \text{for all } x \in \mathcal{S}_A$$

and  $t \geq \tau \geq a$ .

(d) Eqn. (4) has linear asymptotic equilibrium relative to  $P$  if  $\lim_{t \rightarrow \infty} P^{-1}(t)x(t)$  exists and is nonzero for every nontrivial  $x \in \mathcal{S}_A$ .