

## Notes on the Real Symmetric Toeplitz Eigenvalue Problem

W. F. Trench

Following Andrew [1], we say that an  $n$ -vector  $x = [x_1 \ x_2 \ \cdots \ x_n]^T$  is *symmetric* if

$$x_j = x_{n-j+1}, \quad 1 \leq j \leq n,$$

or *skew-symmetric* if

$$x_j = -x_{n-j+1}, \quad 1 \leq j \leq n.$$

(Some authors call such vectors *reciprocal* and *anti-reciprocal*.)

The following theorems are special cases of results stated explicitly by Cantoni and Butler [2], but already implicit in Andrew [1]. (It's important to cite Andrew in this way. Many authors – including Trench – have overlooked the full scope of Andrew's results.) These theorems imply that if  $T$  is an RST matrix of order  $n$  then  $R^n$  has an orthonormal basis consisting of  $\lfloor n/2 \rfloor$  symmetric and  $\lfloor n/2 \rfloor$  skew-symmetric eigenvectors of  $T$ . They also yield efficient methods for computing eigenvalues and eigenvectors of real symmetric Toeplitz matrices.

In [3] I defined an eigenvalue  $\lambda$  of  $T$  to be *even* (*odd*) if  $T$  has a symmetric (skew-symmetric)  $\lambda$ -eigenvector. In the following theorems  $J_m$  is the  $m \times m$  matrix with ones on the secondary diagonal and zeros elsewhere. In the proofs we rely heavily on the relations

$$JJ = I \quad \text{and} \quad JT = TJ$$

if  $T$  is a symmetric Toeplitz matrix.

We can partition  $T_{2m}$  as

$$T_{2m} = \begin{bmatrix} T_m & J_m H_m \\ H_m J_m & T_m \end{bmatrix} \quad (1)$$

where  $H_m = (t_{i+j-1})_{i,j=1}^m$ .

We can partition  $T_{2m+1}$  as

$$T_{2m+1} = \begin{bmatrix} T_m & J_m u_m & J_m G_m \\ u_m^t J_m & t_0 & u_m^t \\ G_m J_m & u_m & T_m \end{bmatrix} \quad (2)$$

where  $G_m = (t_{i+j})_{i,j=1}^m$  and

$$u_m = \begin{bmatrix} t_1 \\ t_2 \\ \vdots \\ t_m \end{bmatrix}.$$

**Theorem 1** Suppose that  $\mu$  is an eigenvalue of

$$A_m = T_m + H_m$$

with associated eigenvector  $x$ . Then  $\mu$  is an even eigenvalue of  $T_{2m}$ , with associated symmetric eigenvector

$$p = \begin{bmatrix} J_m x \\ x \end{bmatrix}.$$

PROOF. From (1),

$$\begin{aligned} T_{2m}p &= \begin{bmatrix} T_m & J_m H_m \\ H_m J_m & T_m \end{bmatrix} \begin{bmatrix} J_m x \\ x \end{bmatrix} \\ &= \begin{bmatrix} (T_m J_m + J_m H_m)x \\ (T_m + H_m)x \end{bmatrix} = \begin{bmatrix} J_m(T_m + H_m)x \\ (T_m + H_m)x \end{bmatrix} = \mu p. \end{aligned}$$

□

**Theorem 2** Suppose that  $\nu$  is an eigenvalue of

$$B_m = T_m - H_m$$

with associated eigenvector  $y$ . Then  $\nu$  is an odd eigenvalue of  $T_{2m}$ , with associated skew-symmetric eigenvector

$$q = \begin{bmatrix} -J_m y \\ y \end{bmatrix}.$$

PROOF. From (1),

$$\begin{aligned} T_{2m}q &= \begin{bmatrix} T_m & J_m H_m \\ H_m J_m & T_m \end{bmatrix} \begin{bmatrix} -J_m y \\ y \end{bmatrix} \\ &= \begin{bmatrix} (-T_m J_m + J_m H_m)y \\ (T_m - H_m)y \end{bmatrix} = \begin{bmatrix} -J_m(T_m - H_m)y \\ (T_m - H_m)y \end{bmatrix} = \nu q. \end{aligned}$$

□

**Theorem 3** Suppose that  $\mu$  is an eigenvalue of

$$C_m = \begin{bmatrix} t_0 & \sqrt{2}u_m^t \\ \sqrt{2}u_m & T_m + G_m \end{bmatrix},$$

with eigenvector  $\begin{bmatrix} \alpha \\ x \end{bmatrix}$ , where  $\alpha$  is a scalar. Then  $\mu$  is an even eigenvalue of  $T_{2m+1}$ , with associated symmetric eigenvector

$$p = \begin{bmatrix} J_m x \\ \alpha \sqrt{2} \\ x \end{bmatrix}.$$

PROOF. From (2),

$$\begin{aligned} T_{2m+1}p &= \begin{bmatrix} T_m & J_m u_m & J_m G_m \\ u_m^t J_m & t_0 & u_m^t \\ G_m J_m & u_m & T_m \end{bmatrix} \begin{bmatrix} J_m x \\ \alpha \sqrt{2} \\ x \end{bmatrix} \\ &= \begin{bmatrix} T_m J_m x + \alpha \sqrt{2} J_m u_m + J_m G_m x \\ u_m^t x + t_0 \alpha \sqrt{2} + u_m^t x \\ G_m x + \alpha \sqrt{2} u_m + T_m x \end{bmatrix} = \mu p. \end{aligned}$$

(Remember that  $T_m J_m = J_m T_m$ .) □

**Theorem 4** Suppose that  $\nu$  is an eigenvalue of

$$D_m = T_m - G_m$$

with eigenvector  $y$ . Then  $\nu$  is an odd eigenvalue of  $T_{2m+1}$ , with associated skew-symmetric eigenvector

$$q = \begin{bmatrix} -J_m y \\ 0 \\ y \end{bmatrix}.$$

PROOF. From (2),

$$\begin{aligned} T_{2m+1}q &= \begin{bmatrix} T_m & J_m u_m & J_m G_m \\ u_m^t J_m & t_0 & u_m^t \\ G_m J_m & u_m & T_m \end{bmatrix} \begin{bmatrix} -J_m y \\ 0 \\ y \end{bmatrix} \\ &= \begin{bmatrix} -T_m J_m y + J_m G_m y \\ -u_m^t y + u_m^t y \\ -G_m y + T_m y \end{bmatrix} = \nu q. \end{aligned}$$

(Remember that  $T_m J_m = J_m T_m$ .) □

Now assume that

$$t_r = \frac{1}{\pi} \int_0^\pi f(\theta) d\theta.$$

Then

$$\begin{aligned} a_{rs} &= \frac{1}{\pi} \int_0^\pi f(\theta) [\cos(r-s)\theta + \cos(r+s-1)\theta] d\theta \\ &= \frac{2}{\pi} \int_0^\pi f(\theta) \cos(r-1/2)\theta \cos(s-1/2)\theta d\theta \quad r, s = 1, \dots, n, \\ b_{rs} &= \frac{1}{\pi} \int_0^\pi f(\theta) [\cos(r-s)\theta - \cos(r+s-1)\theta] d\theta \\ &= \frac{2}{\pi} \int_0^\pi f(\theta) \sin(r-1/2)\theta \sin(s-1/2)\theta d\theta \quad r, s = 1, \dots, n, \end{aligned}$$

$$\begin{aligned}
c_{rs} &= \frac{1}{\pi} \int_0^\pi f(\theta) [\cos(r-s)\theta + \cos(r+s)\theta] d\theta \\
&= \frac{2}{\pi} \int_0^\pi f(\theta) \cos r\theta \cos s\theta d\theta \quad r, s = 1, \dots, n,
\end{aligned}$$

(the zeroth row and column of  $C$  are not included here), and

$$\begin{aligned}
d_{rs} &= \frac{1}{\pi} \int_0^\pi f(\theta) [\cos(r-s)\theta - \cos(r+s)\theta] d\theta \\
&= \frac{2}{\pi} \int_0^\pi f(\theta) \sin r\theta \sin s\theta d\theta \quad r, s = 1, \dots, n.
\end{aligned}$$

## References

- [1] A. L. ANDREW, *Eigenvectors of certain matrices*, Linear Algebra Appl., 7 (1973), pp. 151–162.
- [2] A. CANTONI AND F. BUTLER, *Eigenvalues and eigenvectors of symmetric centrosymmetric matrices*, Linear Algebra Appl., 13 (1976), pp. 275–288.
- [3] W. F. TRENCH, *Spectral evolution of a one-parameter extension of a real symmetric Toeplitz matrix*, SIAM J. Matrix Anal. Appl. 11 (1990), 601-611.